

Unbalanced Riemannian Metric Transport and the Wasserstein-Ebin Metric

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Abstract:

Work with M. Bauer and FX Viallard: We present weak Riemannian metrics on 5 different spaces related to the space of all Riemannian metrics which fit together via Riemannian submersions. Its geodesics are like the unbalanced version of the Brenier-Otto optimal transport with the most interesting version on the space of Riemannian metrics.

The spaces

Let (M, g_0) be a compact manifold equipped with a background Riemannian metric g_0 with $\rho_0 = \text{vol}(g_0)$. Then let

- ▶ $\mathcal{C}(M) = M \times \mathbb{R}_{>0}$, the cone over M .
- ▶ $\text{Dens}(M) = \Gamma_{>0}(|\wedge^d|(T^*M))$ the space of all positive densities on M .
- ▶ $\text{Diff}(M)$ the diffeomorphism group of M .
- ▶ $\text{Met}(M)$ the space of all Riemannian metrics on M .
- ▶ $\text{Gau}(TM) = GL(TM)$ the gauge group of TM ; all vector bundle automorphisms of TM over Id_M .
- ▶ $\text{Aut}(TM)$ the automorphism group of TM . We have a splitting exact sequence

$$\{\text{Id}_{TM}\} \longrightarrow \text{Gau}(TM) \xrightarrow{i} \text{Aut}(TM) \begin{array}{c} \xrightarrow{p: \bar{\varphi} \mapsto \varphi} \\ \xleftarrow{T\varphi \leftarrow \varphi: j} \end{array} \text{Diff}(M) \longrightarrow \{\text{Id}_M\}$$

The semidirect product $\text{Diff}(M) \ltimes \text{Gau}(TM) = \text{Aut}(TM)$ is induced by $(\varphi, \alpha) \mapsto T\varphi \circ \alpha \in \text{Aut}(TM)$ leading to

$$\begin{aligned} (\varphi, \alpha)(\varphi', \alpha') &= (\varphi \circ \varphi', (T\varphi')^{-1} \cdot \alpha \cdot T\varphi' \cdot \alpha'), \\ (\varphi, \alpha)^{-1} &= (\varphi^{-1}, T\varphi \cdot \alpha^{-1} \cdot T\varphi^{-1}). \end{aligned}$$

Theorem

Consider the projections π_i defined via

$$\pi_0 : \begin{cases} \text{Aut}(\mathcal{C}(M)) \rightarrow \text{Dens}(M) \\ (\varphi, \lambda) \mapsto \varphi_*(\lambda^2 \rho_0) \end{cases} \quad \pi_1 : \begin{cases} \text{Met}(M) \rightarrow \text{Dens}(M) \\ g \mapsto \text{vol}(g) \end{cases}$$

$$\pi_2 : \begin{cases} \text{Aut}(TM) \rightarrow \text{Aut}(\mathcal{C}(M)) \\ (\varphi, \alpha) \mapsto (\varphi, \sqrt{|\det \alpha^{-1}|}) \end{cases}$$

$$\pi_3 : \begin{cases} \text{Aut}(TM) \rightarrow \text{Met}(M) \\ (\varphi, \alpha) \mapsto \varphi_* \alpha_* g_0 = \varphi_*(\alpha^{-T} g_0 \alpha^{-1}) \end{cases}$$

$$\pi_4 : \begin{cases} \text{Aut}(TM) \rightarrow \text{Diff}(M) \times \text{Met}(M) \\ (\varphi, \alpha) \mapsto (\varphi, \alpha_* g_0) = (\varphi, \alpha^{-T} g_0 \alpha^{-1}) \end{cases}$$

$$\pi_5 : \begin{cases} \text{Diff}(M) \times \text{Met}(M) \rightarrow \text{Met}(M) \\ (\varphi, g) \mapsto \varphi_* g = (T\varphi)^{-T} g T\varphi^{-1} \end{cases}$$

Then the following is a commutative diagram of Riemannian submersions:

$$\begin{array}{ccc}
 (\text{Aut}(TM), G^{\text{Aut}(TM)}) & \xrightarrow[\pi_4]{(\varphi, \alpha) \mapsto (\varphi, \alpha_* g_0)} & (\text{Diff}(M) \times \text{Met}(M), G^{W \times E}) \\
 \downarrow \pi_2 & \searrow \pi_3 & \downarrow \pi_5 \\
 (\varphi, \alpha) \mapsto (\varphi, \frac{1}{\sqrt{|\det \alpha^{-1}|}}) & (\varphi, \alpha) \mapsto \varphi_* \alpha_* g_0 & (\varphi, g) \mapsto \varphi_* g \\
 (\text{Aut}(\mathcal{C}(M)), G^{\text{Aut}(\mathcal{C}(M))}) & & (\text{Met}(M), G^{WE}) \\
 \searrow \pi_0 & & \downarrow \pi_1 = \text{vol} \\
 (\varphi, \lambda) \mapsto \varphi_*(\lambda^2 \rho_0) & & (\text{Dens}(M), G^{WFR})
 \end{array}$$

where the corresponding Riemannian metrics are given as follows:

$$\begin{aligned} G_{(\varphi, \alpha)}^{\text{Aut}(TM)}((\delta\varphi, \delta\alpha), (\delta\varphi, \delta\alpha)) &= \\ &= \int \left(g_0(\delta\varphi, \delta\varphi) + \frac{d\Lambda}{4} \text{Tr}(g_0\alpha^{-1}\delta\alpha g_0^{-1}\delta\alpha^\top\alpha^{-\top}) \right) |\det(\alpha)|^{-1} \text{vol}(g_0) \end{aligned}$$

$$\begin{aligned} G_{(\varphi, g)}^{W \times E}((\delta\varphi, h), (\delta\varphi, h)) &= \int_M g_0(\delta\varphi, \delta\varphi) \text{vol}(g) \\ &\quad + \frac{d\Lambda}{16} \int_M \text{tr}(g^{-1}hg^{-1}h) \text{vol}(g) \end{aligned}$$

$$G_{\varphi, \lambda}^{\text{Aut}(C(M))}((\delta\varphi, \delta\lambda), (\delta\varphi, \delta\lambda)) = \int_M (\lambda^2 g_0(\delta\varphi, \delta\varphi) + \Lambda(\delta\lambda)^2) \text{vol}(g_0)$$

$$\begin{aligned} G_g^{WE}(\delta g, \delta g) &= \inf_{v, h} \int_M g_0(v, v) \text{vol}(g) + \frac{d\Lambda}{16} \int_M \text{tr}(g^{-1}hg^{-1}h) \text{vol}(g) \\ \text{subject to: } \delta g &= -\mathcal{L}_v g + h \end{aligned}$$

$$\begin{aligned} G_\rho^{WFR}(\delta\rho, \delta\rho) &= \inf_{v, f} \int_M g_0(v, v)\rho + \frac{\Lambda}{4} \int_M f^2\rho \\ \text{subject to: } \delta\rho &= -\mathcal{L}_v\rho + f\rho. \end{aligned}$$

The second summand in the integral in the definition of the metric $G^{\text{Aut}(TM)}$ comes from the left invariant Riemannian metric on $GL(T_x M)$ given by

$$\begin{aligned} G_A^{GL(T_x M), g_0}(X, X) &= \text{tr}(A^{-1} X g_0^{-1} (A^{-1} X)^T g_0) \\ &= \text{tr}(A^{-1} X g_0^{-1} X^T A^{-T} g_0), \end{aligned}$$

where $A^{-T} = (A^{-1})^T = (A^T)^{-1} : T_x^* M \rightarrow T_x^* M$.

Attention: We do not yet have a proof that the Wasserstein-Ebin metric G^{WE} on $\text{Met}(M)$ induces a non-degenerate metric via the infimum of length of curves connecting two points.

Lemma

Let $\varphi(t)$ be a smooth curve of diffeomorphisms on a manifold M locally defined for each t , with $f_0 = \text{Id}_M$. We consider the two time dependent vector fields

$$X(t)(x) := (T_x \varphi(t))^{-1} \partial_t \varphi(t)(x), \quad Y(t)(x) := (\partial_t \varphi(t))(\varphi(t)^{-1}(x)).$$

Then $T(\varphi(t)).X(t) = \partial_t \varphi(t) = Y(t) \circ \varphi(t)$, so $X(t)$ and $Y(t)$ are $\varphi(t)$ -related. Moreover, for any tensor field K on M we have:

$$\partial_t \varphi(t)^* K = \varphi(t)^* \mathcal{L}_{Y(t)} K = \mathcal{L}_{X(t)} \varphi(t)^* K.$$

$$\partial_t \varphi(t)_* K = \partial_t (\varphi(t)^{-1})^* K = -\varphi(t)_* \mathcal{L}_{X(t)} K = -\mathcal{L}_{Y(t)} \varphi(t)_* K.$$

π_0 is a Riemannian submersion

Let $(\varphi, \lambda) \in \text{Aut}(\mathcal{C}(M))$ with $\pi_0(\varphi, \lambda) = \varphi_*(\lambda^2 \rho_0) = \rho$, and let $Y := \delta\varphi \circ \varphi^{-1} \in \mathfrak{X}(M)$. By the lemma we have:

$$\begin{aligned} T_{(\varphi, \lambda)} \pi_0.(\delta\varphi, \delta\lambda) &= -\mathcal{L}_Y \varphi_*(\lambda^2 \rho_0) + \varphi_*(2\lambda. \delta\lambda. \rho_0) \\ &= -\mathcal{L}_Y \rho + \varphi_*(2\frac{\delta\lambda}{\lambda}).\varphi_*(\lambda^2 \rho_0) \\ &= -\mathcal{L}_Y \rho + \varphi_*(2\frac{\delta\lambda}{\lambda}).\rho = -\mathcal{L}_Y \rho + f\rho, \text{ where } f = \varphi_*(2\frac{\delta\lambda}{\lambda}). \end{aligned}$$

For fixed $(\varphi, \lambda) \in \text{Aut}(\mathcal{C}(M))$ with $\pi_0(\varphi, \lambda) = \varphi_*(\lambda^2 \rho_0) = \rho$, i.e., $\rho_0 = \frac{1}{\lambda^2} \varphi^* \rho$, we have to find the infimum of the $G_{\varphi, \lambda}^{\text{Aut}(\mathcal{C}(M))}$ -norm of all $(\delta\varphi, \delta\lambda) \in T_{(\varphi, \lambda)} \text{Aut}(\mathcal{C}(M))$ with

$$-\mathcal{L}_Y \rho + f\rho = T_{(\varphi, \lambda)} \pi_0.(\delta\varphi, \delta\lambda) = \delta\rho \quad \text{Continuity Equation}$$

where $f = \varphi_*(2\frac{\delta\lambda}{\lambda}) \in C^\infty(M, \mathbb{R}_{>0})$.

Fix $(\varphi, \lambda) \in \text{Aut}(\mathcal{C}(M))$ with $\pi_0(\varphi, \lambda) = \varphi_*(\lambda^2 \rho_0) = \rho$, i.e., $\rho_0 = \frac{1}{\lambda^2} \varphi^* \rho$. Search the inf over all $(\delta\varphi, \delta\lambda) \in T_{(\varphi, \lambda)} \text{Aut}(\mathcal{C}(M))$ with $-\mathcal{L}_Y \rho + f\rho = T_{(\varphi, \lambda)} \pi_0.(\delta\varphi, \delta\lambda) = \delta\rho$, where $Y := \delta\varphi \circ \varphi^{-1} \in \mathfrak{X}(M)$ and $f = \varphi_*(2\frac{\delta\lambda}{\lambda}) \in C^\infty(M, \mathbb{R}_{>0})$, of

$$\begin{aligned}
 G_{\varphi, \lambda}^{\text{Aut}(\mathcal{C}(M))}((\delta\varphi, \delta\lambda), (\delta\varphi, \delta\lambda)) &= \int_M (\lambda^2 g_0(\delta\varphi, \delta\varphi) + \Lambda(\delta\lambda)^2) \rho_0 \\
 &= \int_M g_0(\delta\varphi, \delta\varphi) \lambda^2 \rho_0 + \Lambda \int_M \delta\lambda^2 \rho_0 \\
 &= \int_M g_0(\delta\varphi, \delta\varphi) \varphi^* \rho + \Lambda \int_M \frac{\delta\lambda^2}{\lambda^2} \varphi^* \rho \\
 &= \int_M \varphi^* \left(g_0(\delta\varphi \circ \varphi^{-1}, \delta\varphi \circ \varphi^{-1}) \rho \right) + \frac{\Lambda}{4} \int_M \varphi^*(f^2 \rho) \\
 &= \int_M g_0(Y, Y) \rho + \frac{\Lambda}{4} \int_M f^2 \rho \quad \text{subject to } -\mathcal{L}_Y \rho + f\rho = \delta\rho \\
 &= G_\rho^{\text{WFR}}(\delta\rho, \delta\rho)
 \end{aligned}$$

This is independent of the choice of (φ, λ) which satisfy $\pi_0(\varphi, \lambda) = \varphi_*(\lambda^2 \rho_0) = \rho$.

Example Proof: π_5 is a Riemannian submersion

It is obviously a submersion.

$$\pi_5(\varphi, g) = \varphi_* g = T^* \varphi^{-1} \circ g \circ T \varphi^{-1} =: \bar{g}$$

$$T_{(\varphi, g)} \pi_5(\delta \varphi, h) = -\mathcal{L}_Y \varphi_* g + \varphi_* h \quad \text{where } Y = \delta \varphi \circ \varphi^{-1} = \varphi_* X$$

$$\begin{aligned} \pi_5^{-1}(\bar{g}) &= \{(\varphi, g) \in \text{Diff}(M) \times \text{Met}(M) : \varphi_* g = \bar{g}\} \\ &= \{(\varphi, \varphi^* \bar{g}) : \varphi \in \text{Diff}(M)\} \end{aligned}$$

$$T_{(\varphi, \varphi^* \bar{g})} \pi_5^{-1}(\bar{g}) = \{(Y \circ \varphi, \varphi^* \mathcal{L}_Y \bar{g}) : Y \in \mathfrak{X}(M)\}$$

Note the appearance of the continuity equation in $T\pi_5$.

We do not have access to a horizontal bundle, thus we proceed as follows. $\pi_5 : \text{Diff}(M) \times \text{Met}(M) \rightarrow \text{Met}(M)$ is a Riemannian submersion in the sense that

$T_{(\varphi, g)} \pi_5 : T_\varphi \text{Diff}(M) \times T_g \text{Met}(M) \rightarrow T_{\varphi_* g} \text{Met}(M)$ is a norm-quotient mapping independently of φ .

For $g = \varphi^* \bar{g}$ and $k = T_{(\varphi, g)} \pi_5(\delta\varphi, h) = -\mathcal{L}_Y \varphi_* g + \varphi_* h = -\mathcal{L}_Y \bar{g} + \varphi_* h \in T_{\bar{g}} \text{Met}(M)$ we have

$$\begin{aligned}
 \|k\|_{G_{\bar{g}}^{WE}}^2 &= G_{\bar{g}}^{WE}(k, k) = G_{\varphi_* g}^{WE}(T_{(\varphi, g)} \pi_5(\delta\varphi, h), T_{(\varphi, g)} \pi_5(\delta\varphi, h)) \\
 &= \inf \left\{ \int_M g_0(Y, Y) \text{vol}(\bar{g}) + \frac{d\Lambda}{4} \int_M \text{tr}(\bar{g}^{-1} \bar{h} \bar{g}^{-1} \bar{h}) \text{vol}(\bar{g}) : \right. \\
 &\quad \left. Y \in \mathfrak{X}(M), \bar{h} \in T_{\bar{g}} \text{Met}(M) \text{ with } k = -\mathcal{L}_Y \bar{g} + \bar{h} \right\} \\
 &= \inf \left\{ \int_M g_0(Y \circ \varphi, Y \circ \varphi) \text{vol}(g) + \frac{d\Lambda}{4} \int_M \text{tr}(g^{-1} h g^{-1} h) \text{vol}(g) : \right. \\
 &\quad \left. Y \in \mathfrak{X}(M), h = \varphi^* \bar{h} \in T_g \text{Met}(M) \text{ with } k = -\mathcal{L}_Y \bar{g} + \bar{h} \right\}
 \end{aligned}$$

where in the end we applied φ^* to both integrands.

This should be equal to

$$\begin{aligned}
 & \inf \left\{ \|(Y \circ \varphi, h)\|_{G_{(\varphi, g)}^{W \times E}}^2 : (Y \circ \varphi, h) \in T_{\varphi} \text{Diff}(M) \times T_g \text{Met}(M) \right. \\
 & \quad \left. h \in T_g \text{Met}(M), Y \in \mathfrak{X}(M) \text{ with } T_{(\varphi, \varphi^* \bar{g})} \pi_5(Y \circ \varphi, h) = k \right\} \\
 &= \inf \left\{ \int_M g_0(Y \circ \varphi, Y \circ \varphi) \text{vol}(g) + \frac{d\Lambda}{16} \int_M \text{tr}(g^{-1} h g^{-1} h) \text{vol}(g) : \right. \\
 & \quad \left. h \in T_g \text{Met}(M), Y \in \mathfrak{X}(M) \text{ with } -\mathcal{L}_Y \bar{g} + \varphi_* h = k \right\}
 \end{aligned}$$

independently of φ , which is the case since both integrals do not change by applying ψ^* for each fixed φ and g separately, independently of φ . Since squared norms are homogeneous of order 2, that is, $\|tk\|^2 = t^2\|k\|^2$, it also follows that the induced norm on the image by such a Riemannian submersion actually comes from a Riemannian metric. Unfortunately, the horizontal lifts for these Riemannian submersions are not simple: They may lie in a completion of each fiber. □

Thank you for listening.